WORLD INTELLECTUAL PROPERTY ORGANIZATION International Bureau



INTERNATIONAL APPLICATION PUBLISHED UNDER THE PATENT COOPERATION TREATY (PCT)

(51) International Patent Classification 5: WO 92/00124 (11) International Publication Number: " A63B 35/12 (43) International Publication Date: 9 January 1992 (09.01.92)

(21) International Application Number:

PCT/GB91/01007

(22) International Filing Date:

21 June 1991 (21.06.91)

(30) Priority data:

9014021.1

23 June 1990 (23.06.90)

(71)(72) Applicant and Inventor: HANCOCK, Frank, John, Thompson [GB/GB]; Oak Brow, Serotina, Beechfield Road, Alderley Edge, Cheshire SK9 7AT (GB).

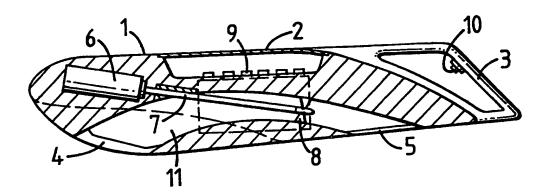
(74) Agent: RUSHTON, Ronald; Sommerville & Rushton, 11 Holywell Hill, St Albans, Herts AL1 1EZ (GB).

(81) Designated States: AT, AT (European patent), AU, BB, BE (European patent), BF (OAPI patent), BG, BJ (OAPI patent), BR, CA, CF (OAPI patent), CG (OAPI patent), CH, CH (European patent), CI (OAPI patent), CM (OAPI patent), DE, DE (European patent), DK, DK (European patent), ES, ES (European patent), FI, FR (European patent), GA (OAPI patent), GB, GB (European patent), GN (OAPI patent), GP, (European patent) tent), GN (OAPI patent), GR (European patent), HU, IT (European patent), JP, KP, KR, LK, LU, LU (European patent), MC, MG, ML (OAPI patent), MR (OAPI patent), MW, NI., NL (European patent), NO, PI., RO, SD, SE, SE (European patent), SN (OAPI patent), SU, TD (OAPI patent), TG (OAPI patent), US.

Published

With international search report.

(54) Title: PROPULSION DEVICE FOR SWIMMERS



(57) Abstract

A propulsion device for moving a person over a water surface comprises a hull (1) containing propulsion means in the form of a propulsion device (8) and drive means (6, 7) for the propulsion device (8) and also having handles (3) for the person to grip so that a person can be towed in a prone position over a water surface. The propulsion device (8) is contained in a through water channel (11) extending in the fore to aft direction for creating a water flow through the channel (11) whereby to propel the device across a water surface. The channel (11) has a downward direction at its exit end when viewed in the "straight ahead" position of the hull so that steering of the device can be achieved by tilting the device through the handles (3) about a fore to aft axis. The drive means comprises at least one permanent magnet motor (6) energised from a battery pack (9) of secondary cells.

FOR THE PURPOSES OF INFORMATION ONLY

Codes used to identify States party to the PCT on the front pages of pamphlets publishing international applications under the PCT.

AT	Austria	28	Spain	MC	Madagascar
AU	Australia	PI	Finland	ML,	Mali
88	Barbados	PR	France	MN	Mongolia
BE	Belgium	GA	Gabon	MR	Mauritania
8F	Burkina Faso	GB	United Kingdom	MW	Malawi
8G	Bulgaria	GN	Guinea	NL	Netherlands
BJ	Benin	GR	Greece	NO	Norway
88	Brazil	HU	Hungary	PL.	Poland
CA	Canada	IT	Italy	RO	Romania
CF	Central African Republic	JP	Japan	SD	Sudan
CG	Congo	KP	Democratic People's Republic	SE	Sweden
CH	Switzerland		of Korea	SN	Senegal
a	Côte d'Ivoire	KR	Republic of Korea	รบ	Soviet Union
CM	Cameroon	u	Licchtenstein	TD	Chad
CS	Czechoslovakia	LK	Sri Lanka	TG	Togo
DB	Germany	EU)	Luxembourg	us	United States of America
DK	Denmark	MC	Monaco		

5

10

15

20

25

- 1 -

PROPULSION DEVICE FOR SWIMMERS

This invention relates to propulsion devices for moving a person over a water surface.

According to the invention the propulsion device comprises a hull containing propulsion means and having handles whereby the device is designed to tow a person in a prone position over a water surface.

The device is designed to give the sensation of body surfing (surfing without a surfboard) and without the necessity of being skilled in the art of surfing and without having to seek out good surfing beaches. Body surfing is exciting as the modest speeds developed when coming in "on a wave" produce heightened sensations of speed due to the person's body being directly in contact with the water.

The hull is preferably provided with a through water channel in the fore to aft direction and containing an impeller or other means for creating a water flow through the channel whereby the device is propelled across a water surface. The inlet end and/or the exit end of the water channel preferably has a downward direction when viewed in the "straight ahead" position of the hull whereby steering of the device out of the "straight ahead" position can be achieved by tilting the device through the handles about a fore to aft axis.

The drive for the device preferably comprises a high power/weight ratio D.C. electric motor or motors supplied

5

10

from a high energy battery or batteries housed within the hull. The motor may be of the permanent magnet type having neodimium iron boron magnets. The battery is for example a nickel cadmium battery.

One advantageous arrangement comprises a plurality of motors mechanically connected together to drive a common propulsion means, the motors being electrically connected to be independently energised from respective battery packs.

Examples of propulsion device in accordance with the invention will now be described by way of example with reference to the accompanying diagrammatic drawings, in which:

Figure 1 is a sectional elevation of a first form of the device.

Figure 2 is a half plan view of the device of Figure 1 taken on a horizontal plane,

Figure 3 is a scrap sectional view of a detail of the device of Figure 1,

Figure 4 is a schematic top plan view of an alternative form of device, and

Figure 5 is a block diagram of the electrical circuitry used in the device of Figure 4.

25 Referring to Figures 1 to 3, the propulsion device comprises a hull in the form of a smooth surfaced pillow shaped buoyant body 1 provided with handles 3 at the rear end. The body 1 has a through water channel or duct 11

5

10

15

20

25

- 3 -

extending in the fore to aft direction from an entry port 4 to an exit port 5. An impeller 8 is located in the duct 11 and extends transversely of it so that when the impeller 8 is driven, water is drawn through the duct to create thrust for propelling the device forwards. The duct 11 is of substantially circular cross-section in the region of the impeller but not of constant area or necessarily of circular cross-section elsewhere. The duct 11 curves in the form of an arc from the front to the rear of the device i.e. in the fore to aft direction so that it has a downward direction at the ports 4 and 5 in the "straight ahead" position of the body 1 shown in Figures 1 to 3.

A high powered electric motor 6 housed within the body 1 drives the impeller 8 via a shaft 7. The motor 6 is powered by a battery pack comprising secondary cells 9 which are disposed within the body 1 of the device. cells 9 are accessible for easy replacement or maintenance through a watertight hatch 2. Flow of current to the motor 6, and therefore thrust produced is controlled by two watertight buttons 10, located one each side on the handles 3. These buttons 10 send signals to a custom made circuit board (not shown) which could be at any convenient Both of the buttons 10 need location within the body 1. to be depressed to sustain a constant speed - releasing one button momentarily causes the speed to be ramped up to maximum and releasing the other causes a corresponding of the speed so that any desired speed ramping down

5

10

15

20

25

- 4 -

between minimum and maximum can be obtained and subsequently held by resuming pressure on both buttons. Releasing both buttons simultaneously causes all power instantly to be cut off from the motor bringing the device quickly to a halt thus preventing any runaway.

Steering is effected by rolling or tilting the device about its longitudinal i.e. its fore to aft axis. When the device has a level "straight ahead" attitude water leaving the exit port 5 provides downward and rearward components of thrust. When the device is tilted a lateral component is added to the thrust and causes the device to deviate to left or right with respect to the operator depending on the direction and tilt.

The chosen method of propulsion by ducted impeller and the method of steering by angling the thrust components result in a perfectly smooth and rounded outline to the device with no extraneous protrusions that could injure the operator or other swimmers. Even the handles 3 could be recessed within the overall hull profile if desired although this might reduce operator comfort slightly. It is also essential that the drag induced by the operator acts behind the exit port 5 and is greater than the drag from the hull surfaces in front of this point in order to obtain correct steering action.

Theoretical calculations backed up by full scale water tank tests have confirmed that sufficient power can be obtained from modern high efficiency DC motors and

5

10

15

20

25

modern secondary storage cells to allow a reasonable operating time at full power on one charge.

Referring now to Figures 4 and 5, the same reference numerals have been used as in Figures 1 to 3 to designate corresponding parts. The body 1 is generally of the same smooth and rounded outline as shown in Figures 1 to 3 and the duct 11 extends through the body in similar manner to that shown in Figures 1 to 3. The handles of the device of Figures 4 and 5 are provided by a rotatable bar 12 furnished with hand grips 13. This bar 12 is connected by a bowden cable 14 which passes through the body 1 via a watertight gland and operates an input control unit 15 in the form of a rheostat situated in a convenient location within the body 1 to control the power output of the device. A return spring 16 ensures that power is shut off if the operator lets go of the hand grips 13.

The device of Figures 4 and 5 has two or more electric motors 6 mechanically coupled to drive the impeller 8 via the shaft 7, the coupling being by means of toothed belts 16 or ordinary V belts. By this means, two or more battery packs 17 (Figure 5) can be used each of which is used independently of the other to energise a respective motor 6, and the charge drawn from each pack will be automatically equalised by the "back EMF effect". This would not be the case if two or more motors 6, each having an independent battery pack were to drive independent impellers. The advantage of separate battery

packs in this application is that high levels of power can be drawn in total without exceeding a dangerously high voltage (around 50 volts) which would be the case if all the cells were connected in series, and without having to connect cells in parallel which is not recommended by battery manufacturers.

5

10

15

20

25

In order to take advantage of this system, it is necessary to have a means of switching or continuously variably controlling the motor/battery systems so that on the power side they are electrically isolated from each other. One means of doing this is shown by the block diagram of Figure 5.

Referring more particularly to Figure 5, each of the motors 6 is powered from a respective one of the battery packs 17 via a respective power output stage 18. Each power output stage 18 provides a pulsed power output to its motor 6 the mark to space ratio of the pulses being varied to vary the power output. The pulse mark to space ratio is controlled by a respective power driver 19 which is energised from a respective one of the battery packs 17 via a low voltage detect unit 20. The unit 20 serves to detect when the associated battery pack 17 is at a predetermined low state of charge to prevent complete discharge of the associated battery packs 17. It also serves to warn the operator of the low state of charge so that he is still able to return to base at low power-Each power driver 19 produces a pulsed output

corresponding to that which is to be produced from its associated power output stage 18. The pulsed output from each power driver 19 provides the control input to the power output stage 18 connected to it; thus each power output stage 18 is in effect a power amplifier. The mark to space ratio of the pulse outputs from the power drivers 19 is controlled by a pulse width modulator 21 variation of this mark to space ratio will vary the mean power supplied to the motors 6 and hence the speed at which the device is propelled through the water. pulse width modulator 21 is in turn controlled by the rheostat 15 whose setting is determined by the position in rotation of the twist grips 13 and hence the bar 12. rheostat 15 and the pulse width modulator 21 are common to both motor control circuits so that each motor 6 has the same control applied to it.

The steering of the device is by tilting the body l as described with reference to Figures 1 to 3.

15

5

10

5

20

25

CLAIMS

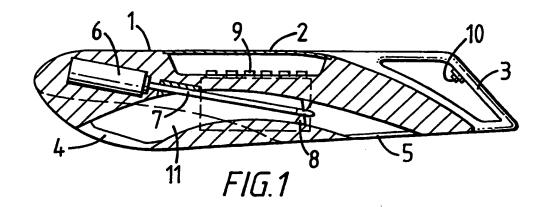
- 1. A propulsion device for moving a person over a water surface comprising a hull (1) containing propulsion means in the form of a propulsion device (8) and drive means (6,7) for the propulsion device (8), and having handles (3,12,13) for the person to grip, whereby the device is designed to tow a person in a prone position over a water surface.
- 10 2. A device according to claim 1, wherein the hull (1) has a through water channel (11) extending in the fore to aft direction and said propulsion device (8) is disposed within the channel (11) for creating a water flow through the channel (11) whereby the device is propelled across the water surface.
 - 3. A device according to claim 2, wherein the inlet end (4) and/or the exit end (5) of the water channel (11) has a downward direction when viewed in the "straight ahead" position of the hull (1) whereby steering of the device out of the "straight ahead" position can be achieved by tilting the device through the handles (3,12,13) about a fore to aft axis.
 - 4. A device according to any preceding claim, wherein the drive means (6,7) include one or more electric motors (6) energised from one or more battery packs (9,17) housed in the hull (1).
 - 5. A device according to claim 4 wherein the or each said electric motor (6) is of the permanent magnet type

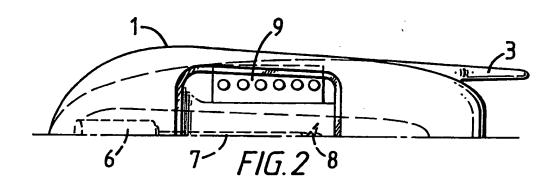
5

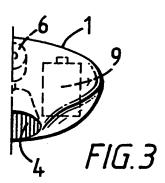
10

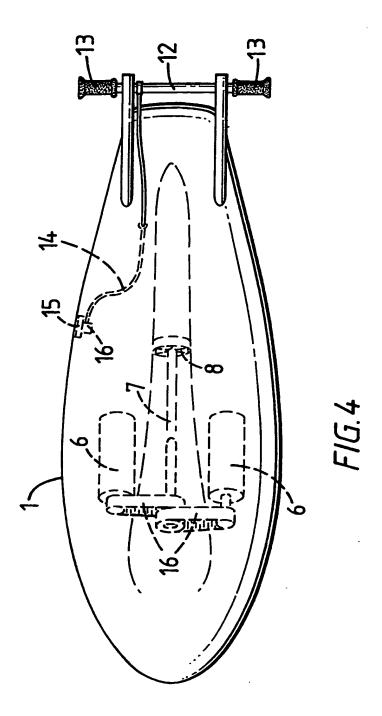
having neodimium iron boron magnets.

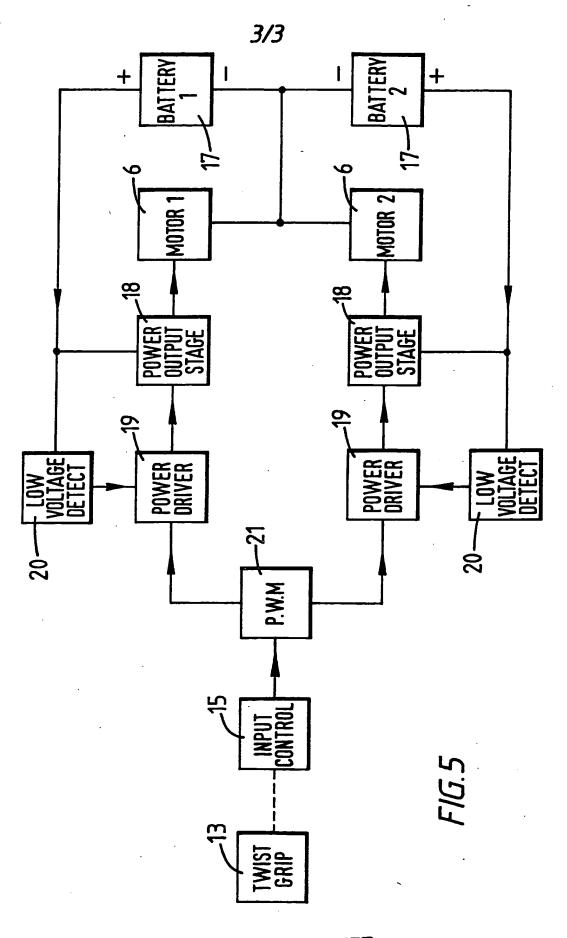
- A device according to claim 4 or 5, wherein the drive means comprises at least two electric motors (6) energised independently from respective battery packs (17) and mechanically connected to drive a common propulsion device (8).
- 7. A device according to claim 6, wherein the power supplied to each motor (6) is controlled by means operable at the handles (3,12,13) to operate an input control unit (15) common to the control circuits (18,19,20,21) of each motor.
- 8. A device according to claim 7 wherein said control circuits (18,19,20,21) include a common pulse width modulator (21) controlled from the input control unit (15).











SHESTITUTE SHEET

International Application No

		at a landing to sum	ols annly, indicate all)	
L CLASSIFI	CATION OF SUBJE	CT MATTER (if several classification symb	Gestion and IPC	
According to Int.C	International Patent 1. 5	Classification (IPC) or to both National Class A63B35/12	and to	
IL FIELDS	PARCHED			
II. PULLUS	TEASURE TO THE PARTY OF THE PAR	Minimum Documents	ntion Searched	
			ssification Symbols	
Chassification	n System			
Int.C	1. 5	A63B		
		Documentation Searches other the to the Extent that such Documents are	n Minimum Documentation Included in the Fields Searched [®]	
		ed to be relevant?		
III. DOCUM	MENTS CONSIDER	D 10 he acceptant	of the relevant passages 12	Relevant to Claim No.13
Category °	Citation of D	ocument, 11 with indication, where appropriate		
х	see pag	564 945 (CHAPOUX) April e 1, left column, line 1 ; figures 1-3	25, 1969 - right column,	1-3
	i		1075	1-4
X Y	see pag	0 565 (LEHMANN) June 22, e 2, line 41 - line 78; e 3, line 15 - line 28	1953 figures 1-2	5
x	see pag	545 222 (MCLEOD) May 2, e 1, line 62 - line 66; e 2, line 21 - line 33 e 2, line 66 - line 67	1979 figures 1-3	1-4
X A	FR,A,66 see pag	0 056 (WILMOUTH) July 6, e 1, line 4 - line 18; f	1929 figures 1–3	1,3,4
A	US,A,3 see col	543 712 (VASILATOS) Dece umn 3, line 24 - line 40	ember 1, 1970 B; figures 1,7	1,2,4
			-/	
° Specia "A" do ca "E" est fil "L" do wh ca "O" do	re the international filing date offict with the application but ple or theory underlying the nest the claimed invention remot be considered to nest the claimed invention we an inventive step when the ne or more other such document or by the considered to a person skilled as patent family			
	FICATION		Date of Mailing of this Intere	entional Search Report
Date of the		f the International Search EMBER 1991	16	10. 91
Internation	al Searching Authorit EUROP	Y PAN PATENT OFFICE	Signature of Authorized Office JONES M.	Marino -

Form PCT/ISA/210 (second sheet) (James y 1985)

DOCUME	NTS CONSIDERED TO BE RELEVANT (CONTINUED FROM THE SECOND SHEET)	,
egory °	Citation of Document, with indication, where appropriate, of the relevant passages	Relevant to Chin No.
-		
Ì	PATENT ABSTRACTS OF JAPAN	5
ł	vol. 13, no. 338 (E-795)(3686) July 28, 1989 & JP-A-1 99 457 (SEIKO EPSON CORP) April 18,	
ļ	• 10_A_1 QQ 457 (SETKO FPSON CORP) April 18,	
ļ	1989	
	see the whole document	
	US,A,3 789 792 (SMITH) February 5, 1974	6
1	see column 3, line 27 - line 33; figures 1-4	i ·
1		
ļ		
- 1		
1		
l	• •	1 .
	•	
]	•	
i	\cdot	
1		,
		**
l		
1	·	
		1
ŀ		
		· ·
l i	•	
1		
1	·	
1		
- 1	· ·	. '
i		·
1		
ļ	•	
l l		
1	••	
į	·	·
ı		
ļ		
İ	•	
i		•
ł		
	·	
		1

ANNEX TO THE INTERNATIONAL SEARCH REPORT ON INTERNATIONAL PATENT APPLICATION NO.

GB 9101007 SA 48870

This annex lists the patent family members relating to the patent documents cited in the above-mentioned international search report.

The members are as contained in the European Patent Office EDP file on

The European Patent Office is in no way liable for these particulars which are merely given for the purpose of information.

30/09/91

Patent document cited in search report	Publication date	Patent family member(s)	Publication date
FR-A-1564945	25-04-69	None	
DE-C-880565		None	
GB-A-1545222	02-05-79	None	
FR-A-660056		None	
US-A-3543712	01-12-70	None	
US-A-3789792	05-02-74	None -	
•			
		•	
	-		

FORM Port

This Page is Inserted by IFW Indexing and Scanning Operations and is not part of the Official Record

BEST AVAILABLE IMAGES

Defective images within this document are accurate representations of the original documents submitted by the applicant.

Defects in the images include but are not limited to the items checked:

BLACK BORDERS

IMAGE CUT OFF AT TOP, BOTTOM OR SIDES

FADED TEXT OR DRAWING

BLURRED OR ILLEGIBLE TEXT OR DRAWING

SKEWED/SLANTED IMAGES

COLOR OR BLACK AND WHITE PHOTOGRAPHS

GRAY SCALE DOCUMENTS

LINES OR MARKS ON ORIGINAL DOCUMENT

REFERENCE(S) OR EXHIBIT(S) SUBMITTED ARE POOR QUALITY

IMAGES ARE BEST AVAILABLE COPY.

☐ OTHER:

As rescanning these documents will not correct the image problems checked, please do not report these problems to the IFW Image Problem Mailbox.